

# Modeling, Identification and Control of Robots (Kogan Page Science Paper Edition)

By W. Khalil, E. Dombre



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Written by two of Europe's leading robotics experts, this book provides the tools for a unified approach to the modelling of robotic manipulators, whatever their mechanical structure.

No other publication covers the three fundamental issues of robotics: modelling, identification and control. It covers the development of various mathematical models required for the control and simulation of robots.

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